AM 255: Problem Set 1

Douglas Lanman 14 September 2006

Problem 1

Let f be a real function with the Fourier series

$$f(x) = \frac{1}{\sqrt{2\pi}} \sum_{\omega = -\infty}^{\infty} \hat{f}(\omega) e^{i\omega x}$$

Prove that

$$S_N = \frac{1}{\sqrt{2\pi}} \sum_{\omega = -N}^{N} \hat{f}(\omega) e^{i\omega x}$$

is real for all N.

First, we note that S_N is real for all N if and only if $S_N = \overline{S}_N$ (i.e., S_N is equal to its complex conjugate \overline{S}_N).

$$S_N = \frac{1}{\sqrt{2\pi}} \sum_{\omega = -N}^{N} \hat{f}(\omega) e^{i\omega x}$$
(1)

$$\overline{S}_N = \frac{1}{\sqrt{2\pi}} \sum_{\omega=-N}^N \overline{\widehat{f}(\omega)} e^{-i\omega x} = \frac{1}{\sqrt{2\pi}} \sum_{\omega=-N}^N \overline{\widehat{f}(-\omega)} e^{i\omega x}$$
(2)

Note that, on the right-hand side (RHS) of Equation 2, we have substituted $\omega \to -\omega$ (since the summation can be taken in any order).

Equating Equations 1 and 2, we find that $\hat{f}(\omega)$ must be *conjugate symmetric* in order for S_N to be a real-valued function for all N (i.e., $\hat{f}(\omega) = \overline{\hat{f}(-\omega)}$). Recall from Equation 1.1.2 in [1], we have

$$\hat{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_0^{2\pi} e^{-i\omega x} f(x) dx = \frac{1}{\sqrt{2\pi}} \ (e^{i\omega x}, f(x)), \tag{3}$$

where on the RHS we have used the definition of the L_2 scalar product norm given by

$$(f,g) = \int_0^{2\pi} \overline{f}g \, dx.$$

Given these definitions, we have

$$\hat{f}(-\omega) = \frac{1}{\sqrt{2\pi}} \int_{0}^{2\pi} e^{i\omega x} f(x) dx = \frac{1}{\sqrt{2\pi}} (e^{-i\omega x}, f(x))$$

$$\Rightarrow \overline{\hat{f}(-\omega)} = \frac{1}{\sqrt{2\pi}} \overline{\int_{0}^{2\pi} e^{i\omega x} f(x) dx} = \frac{1}{\sqrt{2\pi}} \overline{(e^{-i\omega x}, f(x))}$$

$$= \frac{1}{\sqrt{2\pi}} \int_{0}^{2\pi} e^{-i\omega x} \overline{f(x)} dx = \frac{1}{\sqrt{2\pi}} (e^{i\omega x}, \overline{f(x)}).$$
(4)

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Since f is a real function we must have $f(x) = \overline{f(x)}$. Equating Equations 3 and 4, we prove the desired result: if f is a real function, then its Fourier coefficients $\hat{f}(\omega)$ are conjugate symmetric such that $\hat{f}(\omega) = \overline{\hat{f}(-\omega)}$ and, as a result, $S_N = \overline{S}_N$ and S_N must be real for all N.

$$\hat{f}(\omega) = \overline{\hat{f}(-\omega)} \implies S_N = \overline{S}_N, \quad \therefore S_N \text{ is real for all } N$$
(5)

(QED)

Problem 2

Derive estimates for

$$\left| \left(D - \frac{\partial^3}{\partial x^3} \right) e^{i\omega x} \right|$$

where $D = D_+^3$, $D_-D_+^2$, $D_-^2D_+$, D_-^3 , $D_0D_+D_-$.

In this problem we will investigate the approximation of the third partial derivative $\partial^3/\partial x^3$ using several difference operators. To begin our analysis, we evaluate the result analytically.

$$\frac{\partial^3}{\partial x^3}e^{i\omega x} = -i\omega^3 e^{i\omega x} \tag{6}$$

The following Taylor series expansions will also be required in the subsequent analysis.

$$e^{x} = \sum_{n=0}^{\infty} \frac{x^{n}}{n!} = 1 + x + \mathcal{O}(x^{2})$$
$$\sin(x) = \sum_{n=0}^{\infty} \frac{(-1)^{n}}{(2n+1)!} x^{2n+1} = x - \frac{x^{3}}{3!} + \mathcal{O}(x^{5})$$

Finally, we repeat for completeness the forward, backward, and central difference operators in terms of the shift operator E.

$$D_{+} = (E - E^{0})/h, \ D_{-} = (E^{0} - E^{-1})/h, \ \text{and} \ D_{0} = (E - E^{-1})/2h$$

Part (a): $D = D_+^3$

Substituting for the forward difference operator we find

$$\begin{split} D^3_+ e^{i\omega x} &= D^2_+ D_+ e^{i\omega x} = h^{-1} D^2_+ (E - E^0) e^{i\omega x} = h^{-1} (e^{i\omega h} - 1) D^2_+ e^{i\omega x} \\ &= h^{-2} (e^{i\omega h} - 1)^2 D_+ e^{i\omega x} = h^{-3} (e^{i\omega h} - 1)^3 e^{i\omega x}. \end{split}$$

At this point we can substitute the Taylor series expansion for $e^{i\omega h}$ such that

$$D^3_+e^{i\omega x} = h^{-3}(i\omega h + \mathcal{O}(\omega^2 h^2))^3 e^{i\omega x} = (-i\omega^3 + \mathcal{O}(\omega^4 h))e^{i\omega x}.$$

In conclusion, we find that D^3_+ is a first-order accurate approximation of $\partial^3/\partial x^3$ since the error is proportional to h.

$$\left| \left(D_{+}^{3} - \frac{\partial^{3}}{\partial x^{3}} \right) e^{i\omega x} \right| = \mathcal{O}(\omega^{4}h)$$
(7)

Part (b): $D = D_- D_+^2$

Substituting for the forward and backward difference operators we find

$$D_{-}D_{+}^{2}e^{i\omega x} = D_{-}D_{+}D_{+}e^{i\omega x} = h^{-1}D_{-}D_{+}(E - E^{0})e^{i\omega x} = h^{-1}(e^{i\omega h} - 1)D_{-}D_{+}e^{i\omega x}$$
$$= h^{-2}(e^{i\omega h} - 1)^{2}D_{-}e^{i\omega x} = h^{-3}(e^{i\omega h} - 1)^{2}(1 - e^{-i\omega h})e^{i\omega x}.$$

At this point we can substitute the Taylor series expansions for $e^{\pm i\omega h}$ such that

$$D_{-}D_{+}^{2}e^{i\omega x} = h^{-3}(i\omega h + \mathcal{O}(\omega^{2}h^{2}))^{2}(i\omega h + \mathcal{O}(\omega^{2}h^{2}))e^{i\omega x} = (-i\omega^{3} + \mathcal{O}(\omega^{4}h))e^{i\omega x}.$$

In conclusion, we find that $D_-D_+^2$ is a first-order accurate approximation of $\partial^3/\partial x^3$ since the error is proportional to h.

$$\left| \left(D_{-}D_{+}^{2} - \frac{\partial^{3}}{\partial x^{3}} \right) e^{i\omega x} \right| = \mathcal{O}(\omega^{4}h)$$
(8)

Part (c): $D = D_{-}^{2}D_{+}$

Substituting for the forward and backward difference operators we find

$$D_{-}^{2}D_{+}e^{i\omega x} = h^{-1}D_{-}^{2}(E - E^{0})e^{i\omega x} = h^{-1}(e^{i\omega h} - 1)D_{-}D_{-}e^{i\omega x}$$
$$= h^{-2}(e^{i\omega h} - 1)(1 - e^{-i\omega h})D_{-}e^{i\omega x} = h^{-3}(e^{i\omega h} - 1)(1 - e^{-i\omega h})^{2}e^{i\omega x}.$$

At this point we can substitute the Taylor series expansions for $e^{\pm i\omega h}$ such that

$$D_{-}^{2}D_{+}e^{i\omega x} = h^{-3}(i\omega h + \mathcal{O}(\omega^{2}h^{2}))(i\omega h + \mathcal{O}(\omega^{2}h^{2}))^{2}e^{i\omega x} = (-i\omega^{3} + \mathcal{O}(\omega^{4}h))e^{i\omega x}.$$

In conclusion, we find that $D_{-}^2 D_{+}$ is a first-order accurate approximation of $\partial^3 / \partial x^3$ since the error is proportional to h.

$$\left| \left(D_{-}^{2} D_{+} - \frac{\partial^{3}}{\partial x^{3}} \right) e^{i\omega x} \right| = \mathcal{O}(\omega^{4} h)$$
(9)

Part (d): $D = D_{-}^{3}$

Substituting for the backward difference operator we find

$$D_{-}^{3}e^{i\omega x} = h^{-1}D_{-}^{2}(E^{0} - E^{-1})e^{i\omega x} = h^{-1}(1 - e^{-i\omega h})D_{-}D_{-}e^{i\omega x}$$
$$= h^{-2}(1 - e^{-i\omega h})^{2}D_{-}e^{i\omega x} = h^{-3}(1 - e^{-i\omega h})^{3}e^{i\omega x}.$$

At this point we can substitute the Taylor series expansions for $e^{-i\omega h}$ such that

$$D_{-}^{3}e^{i\omega x} = h^{-3}(i\omega h + \mathcal{O}(\omega^{2}h^{2}))^{3}e^{i\omega x} = (-i\omega^{3} + \mathcal{O}(\omega^{4}h))e^{i\omega x}$$

In conclusion, we find that D_{-}^{3} is a first-order accurate approximation of $\partial^{3}/\partial x^{3}$ since the error is proportional to h.

$$\left| \left(D_{-}^{3} - \frac{\partial^{3}}{\partial x^{3}} \right) e^{i\omega x} \right| = \mathcal{O}(\omega^{4}h)$$
(10)

Part (e): $D = D_0 D_+ D_-$

Substituting for the forward, backward, and central difference operators we find

$$D_0 D_+ D_- e^{i\omega x} = h^{-1} D_0 D_+ (E^0 - E^{-1}) e^{i\omega x} = h^{-1} (1 - e^{-i\omega h}) D_0 D_+ e^{i\omega x}$$

= $h^{-2} (1 - e^{-i\omega h}) (e^{i\omega h} - 1) D_0 e^{i\omega x}$
= $ih^{-3} (1 - e^{-i\omega h}) (e^{i\omega h} - 1) \left(\frac{e^{i\omega h} - e^{-i\omega h}}{2i}\right) e^{i\omega x}$
= $ih^{-3} (1 - e^{-i\omega h}) (e^{i\omega h} - 1) \sin(\omega h) e^{i\omega x}.$

At this point we can substitute the Taylor series expansions for $e^{\pm i\omega h}$ and $\sin(\omega h)$ such that

$$D_0 D_+ D_- e^{i\omega x} = ih^{-3}(i\omega h + \mathcal{O}(\omega^2 h^2))(i\omega h + \mathcal{O}(\omega^2 h^2))(\omega h + \mathcal{O}(\omega^3 h^3))e^{i\omega x}$$
$$= (-i\omega^3 + \mathcal{O}(\omega^5 h^2))e^{i\omega x}.$$

In conclusion, we find that $D_0 D_+ D_-$ is a second-order accurate approximation of $\partial^3 / \partial x^3$ since the error is proportional to h^2 .

$$\left| \left(D_0 D_+ D_- - \frac{\partial^3}{\partial x^3} \right) e^{i\omega x} \right| = \mathcal{O}(\omega^5 h^2)$$
(11)

Problem 3

Compute $||D_+D_-||_h$.

We will begin by deriving an upper bound on the discrete norm for periodic gridfunctions. Given two operators P and Q, Equation 1.2.12 in [1] gives

$$\|PQ\|_h \le \|P\|_h \|Q\|_h.$$

Also from page 22 in [1], we have

$$||D_+||_h \le 2/h$$
 and $||D_-||_h \le 2/h$.

Substituting, we find the following upper bound for the discrete operator norm of D_+D_- .

$$\|D_{+}D_{-}\|_{h} \le \|D_{+}\|_{h} \|D_{-}\|_{h} \le 4/h^{2}$$
(12)

We can prove that the inequality in Equation 12 can be replaced with an equality by selecting a specific periodic gridfunction u. Let us begin by substituting for the forward and backward difference operators in terms of the shift operator E.

$$D_{+} = (E - E^{0})/h$$
 and $D_{-} = (E^{0} - E^{-1})/h$

Substituting for D_+ and D_- we find the following result.

$$(D_{+}D_{-}u)_{j} = h^{-2}((E - 2E^{0} + E^{-1})u)_{j} = h^{-2}(u_{j+1} - 2u_{j} + u_{j-1})$$

The definition of the discrete scalar product and norm for periodic gridfunctions are given as follows.

$$(u, v)_h = \sum_{j=0}^N \overline{u}_j v_j h \text{ and } ||u||_h^2 = (u, u)_h$$

As a result, we have

$$\|D_{+}D_{-}u\|_{h}^{2} = \sum_{j=0}^{N} \left(\frac{\overline{u}_{j+1} - 2\overline{u}_{j} + \overline{u}_{j-1}}{h^{2}}\right) \left(\frac{u_{j+1} - 2u_{j} + u_{j-1}}{h^{2}}\right) h$$
$$= \frac{1}{h^{3}} \sum_{j=0}^{N} (\overline{u}_{j+1} - 2\overline{u}_{j} + \overline{u}_{j-1})(u_{j+1} - 2u_{j} + u_{j-1}).$$

Motivated by the example on page 23 of [1], we define $u_j = (-1)^j$ such that

$$\|u\|_{h}^{2} = (N+1)h$$
(13)

$$\|D_{+}D_{-}u\|_{h}^{2} = \frac{1}{h^{3}} \sum_{j=0}^{N} ((-1)^{j+1} - 2(-1)^{j} + (-1)^{j-1})^{2}$$

$$= \frac{1}{h^{3}} \sum_{j=0}^{N} 16 = \frac{16(N+1)}{h^{3}} = \frac{16}{h^{4}} \|u\|_{h}^{2}$$

$$\Rightarrow \|D_{+}D_{-}u\|_{h} = \frac{4}{h^{2}} \|u\|_{h}.$$
(14)

Recall that the discrete norm of an operator Q is given by

$$||Q||_h = \sup_{u \neq 0} ||Qu||_h / ||u||_h.$$

Combining Equations 13 and 14 we find

$$||D_+D_-u||_h/||u||_h = 4/h^2$$
, for $u_j = (-1)^j$. (15)

In conclusion, we have found a "witness" gridfunction $u_j = (-1)^j$ which achieves the upper bound in Equation 12. By the definition of the discrete operator norm, we conclude

$$||D_+D_-||_h = 4/h^2 \tag{16}$$

References

[1] Bertil Gustafsson, Heinz-Otto Kreiss, and Joseph Oliger. *Time Dependent Problems and Difference Methods*. John Wiley & Sons, 1995.